

### 3V to 5.5V, 50Mbps Half Duplex RS485 Transceivers

#### **GENERAL DESCRIPTION**

SiLM1450L is a noise-immune, half duplex RS485/RS422 transceiver designed to operate in rugged industrial environments. The bus pins of the device are robust to high levels of electrostatic discharge (ESD) events. The fail-safe circuitry guarantees a logic high receiver output when the receiver inputs are open or short.

The SiLM1450L operates from a single supply between 3 V and 5.5 V. It features an extended common-mode voltage range which makes it suitable for multi-point applications over long cable runs.

The SiLM1450L is available in SOP8 package for space constrained applications and it supports ambient temperatures from -40°C to 125°C.

#### **APPLICATION**

- Motor driver
- Factory automation and control
- Grid infrastructure
- Building automation
- HVAC systems
- Video surveillance
- Process analytics

#### **FEATURES**

- Meets or exceeds the requirements of the TIA/EIA-485 standard
- 50Mbps data rates, half duplex
- 3V to 5.5V supply voltage
- Differential output exceeds 2.1V for PROFIBUS compatibility with 5V supply
- Extended operational common mode range: ±15V
- Large receiver hysteresis for noise rejection
- Low power consumption
  - Standby supply current: <1uA</li>
  - Current during operation: <2mA</li>
- Ambient temperature: -40°C to 125°C
- Glitch free power up/down for hot plug-in capability
- · Open, short and idle bus failsafe
- 1/8 unit load (up to 256 bus nodes)

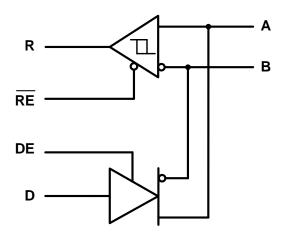


Figure 1. SiLM1450L simplified schematic





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### **PIN CONFIGURATION**

Package	Pin Configuration (Top View)	
SOP8	R	8 VCC 7 B 6 A 5 GND

#### **PIN DESCRIPTION**

No.	Pin Name	Description
1	R	Receive data output
2	RE	Receiver enable, active low, internal pull up.
3	DE	Driver enable, active high, internal pull down
4	D	Driver data input
5	GND	Device ground
6	А	Bus I/O port, A (complementary to B)
7	В	Bus I/O port, B (complementary to A)
8	VCC	Power supply



# **FUNCTIONAL BLOCK DIAGRAM**

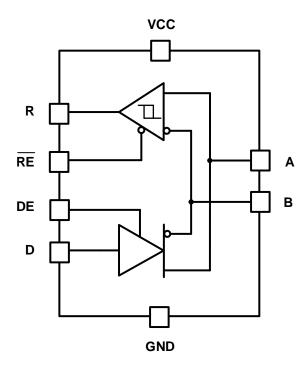


Figure 2. SiLM1450L Block Diagram

### **ORDERING INFORMATION**

Order Part No.	Package	QTY
SiLM1450LCA-DG	SOP8, Pb-Free	2500/Reel



### **ABSOLUTE MAXIMUM RATINGS**

Symbol	Definition	Min	Max	Units
Vcc	Supply Voltage	-0.3	6	V
Vı	Voltage range at any bus pin (A, B) as differential or common mode with respect to GND	-18	18	V
Vin	Voltage at any logic pin (D, DE or RE )	-0.3	6	V
lor	Receiver output current	-24	24	mA
ΤJ	Junction Temperature	-55	150	°C
Ts	Storage Temperature	-65	150	

### **RECOMMENDED OPERATION CONDITIONS**

Symbol	Definition	Min	Max	Units
Vcc	Supply Voltage	3	5.5	V
Vı	Input voltage at any bus terminal	-15	15	V
V <sub>ID</sub>	Differential input voltage	-15	15	V
V <sub>IH</sub>	High level input voltage (D, DE or RE )	2	Vcc	V
VIL	Low level input voltage (D, DE or RE )	0	0.8	V
lo	Driver output current	-60	60	mA
lor	Receiver output current	-8	8	mA
R∟	Differential load resistance	54		Ω
1/t∪ı	Signaling rate		50	Mbps
TJ	Junction Temperature	-40	150	°C
TA	Ambient Temperature	-40	125	°C

### **ESD RATINGS**

Symbol	Definition	Value	Units
	HBM: Bus pins to GND	±20	kV
V <sub>ESD</sub>	HBM: All other pins	±3.5	kV
	CDM	±2	kV



# **ELECTRICAL CHARACTERISTICS (DC)**

All typical values at  $V_{CC}$  = 5V and  $T_A$  = 25°C, all min and max specifications are at recommended operating conditions and  $T_J$  = -40°C to 125°C, unless otherwise specified.

Symbol	Parameter	Condition	Min	Тур	Max	Unit
Driver	1	1	1	I	1	
V <sub>OD1</sub>		R <sub>L</sub> =60Ω, -15V $\leq$ V <sub>TEST</sub> $\leq$ 15V, see Figure 3	1.5	3		V
V <sub>OD2</sub>	Driver differential output voltage	$R_L$ =60 $\Omega$ , -15 $V \le V_{TEST} \le$ 15 $V$ , 4.5 $V \le V_{CC} \le$ 5.5 $V$ , see Figure 3	2.1	3		V
V <sub>OD3</sub>	Vollago	$R_L$ =100 $\Omega$ , see Figure 4	1.8	3.6		V
V <sub>OD4</sub>		$R_L$ =54Ω, see Figure 4	1.5	3.1		V
Δ Vod	Change in differential output voltage		-100		100	mV
Voc	Common mode output voltage	R <sub>L</sub> =54Ω, see Figure 4	1	Vcc/2	3	V
∆VOC(SS)	Change in steady state common mode output voltage		-100		100	mV
los	Short circuit output current	DE=VCC, -7V ≤ V <sub>0</sub> ≤ 12V	-250		250	mA
Receiver						
l <sub>l1</sub>		DE=0V, VCC=0V or 5.5V, V <sub>I</sub> =12V, T <sub>J</sub> = -40°C to 85°C		75	125	uA
II1		DE=0V, VCC=0V or 5.5V, V <sub>I</sub> =12V, T <sub>J</sub> = -40°C to 125°C		75	400	uA
l		DE=0V, VCC=0V or 5.5V, V <sub>I</sub> = -7V, T <sub>J</sub> = -40°C to 85°C	-100	-70		uA
l <sub>l2</sub>	Bus input current	DE=0V, VCC=0V or 5.5V, V <sub>I</sub> = -7V T <sub>J</sub> = -40°C to 125°C	-350	-70		uA
lue		DE=0V, VCC=0V or 5.5V, V <sub>I</sub> =15V, T <sub>J</sub> = -40°C to 85°C		95	140	uA
l <sub>13</sub>		DE=0V, VCC=0V or 5.5V, V <sub>I</sub> =15V, T <sub>J</sub> = -40°C to 125°C		95	450	uA
<b>I</b> 14		DE=0V, VCC=0V or 5.5V, V <sub>I</sub> = -15V, T <sub>J</sub> = - 40°C to 85°C	-200	-120		uA



Symbol	Parameter	Condition	Min	Тур	Max	Unit
		DE=0V, VCC=0V or 5.5V, V <sub>I</sub> = -15V, T <sub>J</sub> = - 40°C to 125°C	-450	-120		uA
V <sub>TH+</sub>	Positive going input threshold voltage			-105	-20	mV
V <sub>TH</sub> -	Negative going input threshold voltage	Over common mode range of ±15V	-200	-130		mV
V <sub>HYS</sub>	Input hysteresis			25		mV
V <sub>ОН</sub>	Output high voltage	I <sub>OH</sub> = -8mA	V <sub>CC</sub> - 0.4	V <sub>CC</sub> - 0.2		V
Vol	Output low voltage	Iон = 8mA		0.2	0.4	V
lozr	Output high impedance current	V <sub>0</sub> =0V or V <sub>CC</sub> , RE =V <sub>CC</sub>	-1		1	uA
Logic						
lin	Input current (D, DE, RE )	$3V \le V_{CC} \le 5.5V$ , $0V \le V_{IN} \le V_{CC}$	-6		6	uA
Supply Curr	ent		•			
I <sub>CC1</sub>	Supply current with driver and receiver enabled	RE =0V, DE=Vcc, No load		1.5	2	mA
I <sub>CC2</sub>	Supply current with driver enabled and receiver disabled	RE =Vcc, DE=Vcc, No load		1.35	1.8	mA
I <sub>CC3</sub>	Supply current with driver disabled and receiver enabled	RE =0V, DE=0V, No load		480	700	uA
I <sub>CC4</sub>	Supply current with driver and receiver disabled	RE =Vcc, DE=0V, D=open, No load		0.1	1	uA
Thermal Pro	tection		•		•	
T <sub>TSD</sub>	Thermal Shutdown Temperature			170		°C
T <sub>HYS</sub>	Thermal Shutdown Hysteresis			15		°C



# **SWITCHING CHARACTERISTICS (AC)**

All typical values at  $V_{CC}$  = 5V and  $T_A$  = 25°C, all min and max specifications are at recommended operating conditions and  $T_J$  = -40°C to 125°C, unless otherwise specified.

Symbol	Parameter	Condition	Min	Тур	Max	Unit
Driver			•			
t <sub>r</sub> , t <sub>f</sub>	Differential output rise/fall time			2	8	ns
t <sub>PHL</sub> , t <sub>PLH</sub>	Propagation delay	$R_L$ =54 $\Omega$ , $C_L$ =50pF, see Figure 5		10	20	ns
tsk(P)	Pulse skew,  tphl-tplh				6	ns
t <sub>PHZ</sub> , t <sub>PLZ</sub>	Disable time			10	20	ns
t <sub>PZH</sub> , t <sub>PZL</sub> Enable time	Enable time	RE =0V, see Figure 6 and Figure 7		10	25	ns
trzn, trzi		RE =Vcc, see Figure 6 and Figure 7		8	15	us
Receiver						
t <sub>r</sub> , t <sub>f</sub>	Output rise/fall time			2	6	ns
t <sub>PHL</sub> , t <sub>PLH</sub>	Propagation delay	C <sub>L</sub> =15pF, see Figure 8		20	35	ns
tsk(P)	Pulse skew,  tphl-tplh				7	ns
t <sub>PHZ</sub> , t <sub>PLZ</sub>	Disable time			8	15	ns
t <sub>PZH1</sub> , t <sub>PZL1</sub> ,	Early Co.	DE=V <sub>CC</sub> , see Figure 9		8	15	ns
tpzH2, tpzL2	Enable time	DE=0V, see Figure 10		9	15	us



#### PARAMETER MEASUREMENT INFORMATION

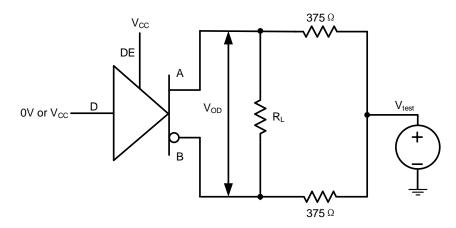


Figure 3. Measurement of driver differential output voltage with common mode load

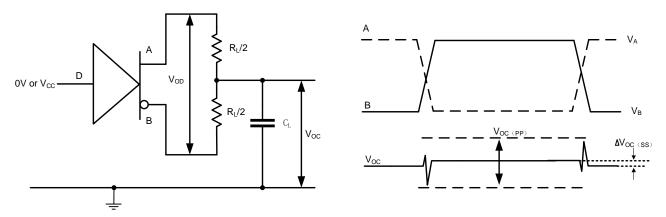


Figure 4. Measurement of driver differential and common mode output with RS485 Load

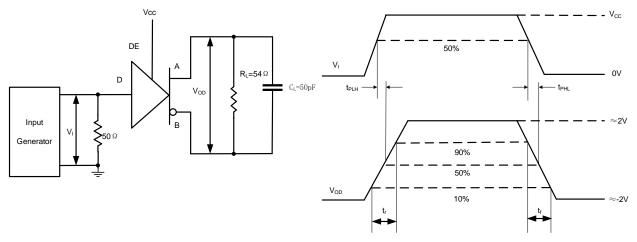


Figure 5. Measurement of driver differential output rise and fall times and propagation delays



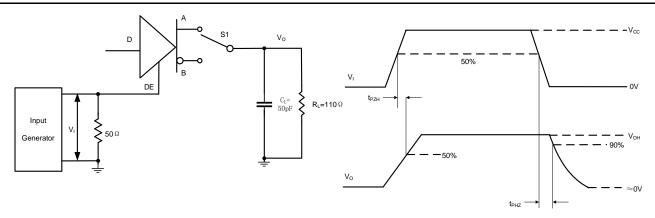


Figure 6. Measurement of driver enable and disable times with active high output and pull-down load

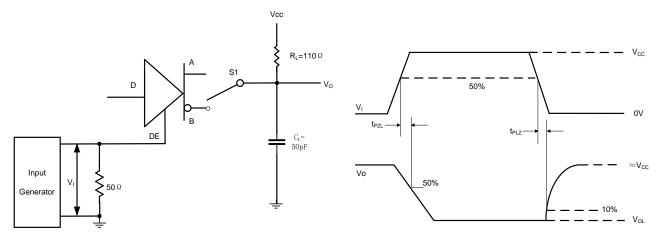


Figure 7. Measurement of driver enable and disable times with active low output and pull-up load

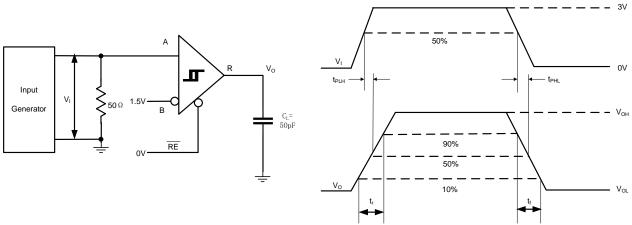


Figure 8. Measurement of receiver output rise and fall times and propagation delays



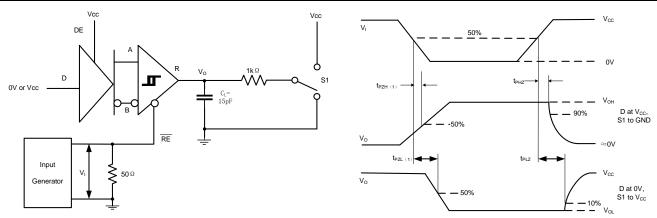


Figure 9. Measurement of receiver enable/disable times with driver enabled

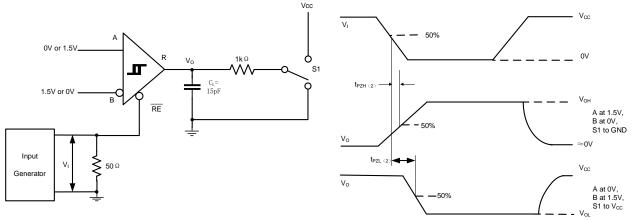


Figure 10. Measurement of receiver enable times with driver disabled



#### FEATURE DESCRIPTION

SiLM1450L is a half-duplex RS-485 transceiver with data transmission up to 50 Mbps. It has active-high driver enable and active low receiver enable. A standby current of less than 1  $\mu$ A can be achieved by disabling both driver and receiver. The SiLM1450L has a higher typical differential output voltage (Vod) than traditional transceivers for better noise immunity. A minimum differential output voltage of 2.1 V is specified with Vcc voltage of 5 V  $\pm$ 10% to meet the requirements of PROFIBUS applications.

The SiLM1450L provides internal biasing of the receiver input thresholds in combination with large input-threshold hysteresis. The receiver output remains logic high under a bus-idle or bus-short conditions without the need for external failsafe biasing resistors. Device operation is specified over a wide ambient temperature range from –40°C to 125°C.

#### **Device Functional Modes**

When the driver enable pin, DE, is logic high, the differential outputs A and B follow the logic states at data input D. A logic high at D causes A to turn high and B to turn low. In this case the differential output voltage defined as  $V_{OD} = V_A - V_B$  is positive. When D is low, the output states reverse: B turns high, A becomes low, and  $V_{OD}$  is negative. When DE is low, both outputs turn high-impedance. In this condition the logic state at D is irrelevant. The DE pin has an internal pull-down resistor to ground, thus when left open the driver is disabled (high-impedance) by default. The D pin has an internal pull-up resistor to VCC, thus, when left open while the driver is enabled, output A turns high and B turns low.

Table 1. Driver function table for SiLM1450L

Input	Enable	Outp	outs	Function
D	DE	Α	В	Function
Н	Н	Н	L	Actively drive bus high
L	Н	L	Н	Actively drive bus low
Х	L	Z	Z	Driver disabled
Х	Open	Z	Z	Driver disabled by default
Open	Н	Н	L	Actively drive bus high by default

When the receiver enable pin,  $\overline{RE}$ , is logic low, the receiver is enabled. When the differential input voltage defined as  $V_{ID} = V_A - V_B$  is higher than the positive input threshold,  $V_{TH+}$ , the receiver output, R, turns high. When  $V_{ID}$  is lower than the negative input threshold,  $V_{TH-}$ , the receiver output, R, turns low. If  $V_{ID}$  is between  $V_{TH+}$  and  $V_{TH-}$  the output is indeterminate.

When  $\overline{RE}$  is logic high or left open, the receiver output is high-impedance and the magnitude and polarity of  $V_{ID}$  are irrelevant. Internal biasing of the receiver inputs causes the output to go failsafe-high when the transceiver is disconnected from the bus (open-circuit), the bus lines are shorted to one another (short-circuit), or the bus is not actively driven (idle bus).

Table 2. Receiver function table for SiLM1450L

Differential Input	Enable	Output	
V <sub>ID</sub> =V <sub>A</sub> -V <sub>B</sub>	RE	R	- Function
V <sub>TH+</sub> <v<sub>ID</v<sub>	L	Н	Receive valid bus high
V <sub>TH-</sub> <v<sub>ID <v<sub>TH+</v<sub></v<sub>	L	unknow	Indeterminate bus state
V <sub>ID</sub> <v<sub>TH-</v<sub>	L	L	Receive valid bus low
Х	Н	Z	Receiver disabled



Х	Open	Z	Receiver disabled by default
Open circuit bus	L	Н	Fail-safe high output
Short circuit bus	L	Н	Fail-safe high output
Idle (terminated) bus	L	Н	Fail-safe high output

#### Receiver Failsafe

The differential receiver of the SiLM1450L is failsafe to invalid bus states caused by the following:

- · Open bus conditions, such as a disconnected connector
- · Shorted bus conditions, such as cable damage shorting the twisted-pair together
- · Idle bus conditions that occur when no driver on the bus is actively driving

In any of these cases, the differential receiver will output a failsafe logic high state so that the output of the receiver is not indeterminate.

Receiver failsafe is accomplished by offsetting the receiver thresholds such that the input indeterminate range does not include zero volts differential. In order to comply with the RS-422 and RS-485 standards, the receiver output must output a high when the differential input  $V_{ID}$  is more positive than 200 mV, and must output a low when  $V_{ID}$  is more negative than -200 mV. The receiver parameters which determine the failsafe performance are  $V_{TH+}$ ,  $V_{TH-}$ , and  $V_{HYS}$  (the separation between  $V_{TH+}$  and  $V_{TH-}$ ). As shown in the Electrical Characteristics (DC) table, differential signals more negative than -200 mV will always cause a low receiver output, and differential signals more positive than 200 mV will always cause a high receiver output.

When the differential input signal is close to zero, it is still above the  $V_{TH+}$  threshold, and the receiver output will be high. Only when the differential input is more than  $V_{HYS}$  below  $V_{TH+}$  will the receiver output transition to a low state. Therefore, the noise immunity of the receiver inputs during a bus fault condition includes the receiver hysteresis value,  $V_{HYS}$ , as well as the value of  $V_{TH+}$ .



#### TYPICAL APPLICATION

The SiLM1450L is a half-duplex RS-485 transceiver and the driver and receiver enable pins allow for the configuration of different operating modes.

RS-485 bus consists of multiple transceivers connecting in parallel to a bus cable as shown in Figure 11. To eliminate line reflections, each cable end is terminated with a termination resistor,  $R_T$ , whose value matches the characteristic impedance,  $Z_0$ , of the cable. This method, known as parallel termination, generally allows for higher data rates over longer cable length.

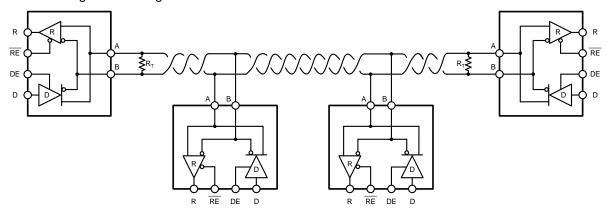
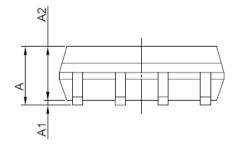
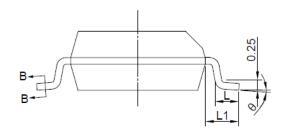


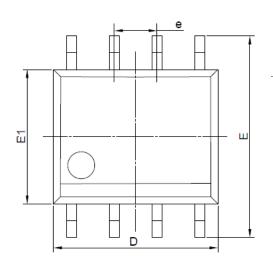
Figure 11. Typical RS-485 Network with Half-Duplex Transceivers

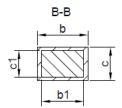


# **PACKAGE CASE OUTLINES**









Dimension	MIN	NOM	MAX	
Α	-	-	1.75	
A1	0.1	-	0.25	
A2	1.25	-	-	
L	0.4	0.835	1.27	
L1	-	1.04	-	
θ	0	-	8	
b	0.31	-	0.51	
b1	0.28	-	0.48	
С	0.1	-	0.25	
c1	0.1	-	0.25	
D	4.7	4.9	5.1	
Е	5.8	6	6.2	
E1	3.8	3.9	4	
е	1.02	1.27	1.52	
Unit : mm				

Figure 12. SOP8 Package Outline Dimensions



#### **REVISION HISTORY**

Note: page numbers for previous revisions may differ from page numbers in current version

Page or Item	Subjects (major changes since previous revision)		
Rev 1.0 datasheet: 2025-03-04			
Whole document	Rev1.0 datasheet release		